



Aerial Robot for Sewer Inspection



Daniel Serrano
Head of Autonomous Systems
Eurecat Technology Center
Barcelona (Spain)
daniel.serrano@eurecat.org

Innovant amb les empreses

ECHORD++ PDTI

Urban Robotics Challenge

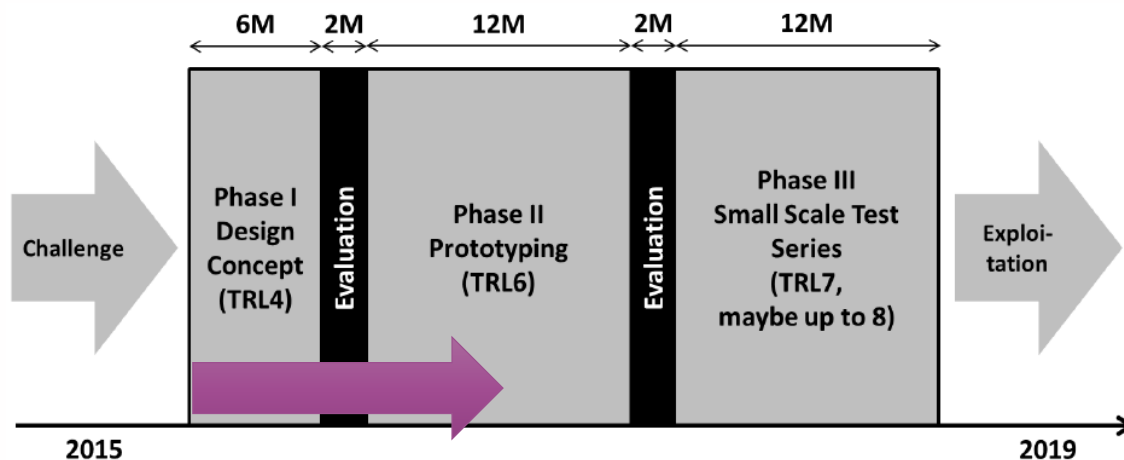
Robots for the inspection of the sewer network in cities



ECHORD++ stimulates the interaction between robot manufacturers, researchers and users.

The **city of Barcelona** has provided its sewer network as use-case and test site.

Together they define the **technical requirements**



Scenario

Urban Robotics Challenge



ARSI Consortium

Urban Robotics Challenge

The consortium covers the entire value chain including:

- FCC: world reference company in environmental urban services.
- EURECAT: Research Centre with experience in both aerial robots for harsh environment and perception.
- SIMTECH: company specialised in aerial robots operation, manufacturing, simulation and training.
- IBAK: worldwide leader in sewer inspection robots manufacturing



ARSI Concept

Urban Robotics Challenge



ARSI is composed by:

- four spherical cameras for structural assessment
- LED based illumination
- range sensor for reactive navigation with specialized planners
- air and gas monitoring sensors
- constant live communications

Sewer inspection in realistic environment

Urban Robotics Challenge



<https://youtu.be/AeK-dMsfpQw>

Phase 2 Developing autonomy – Assistive modes

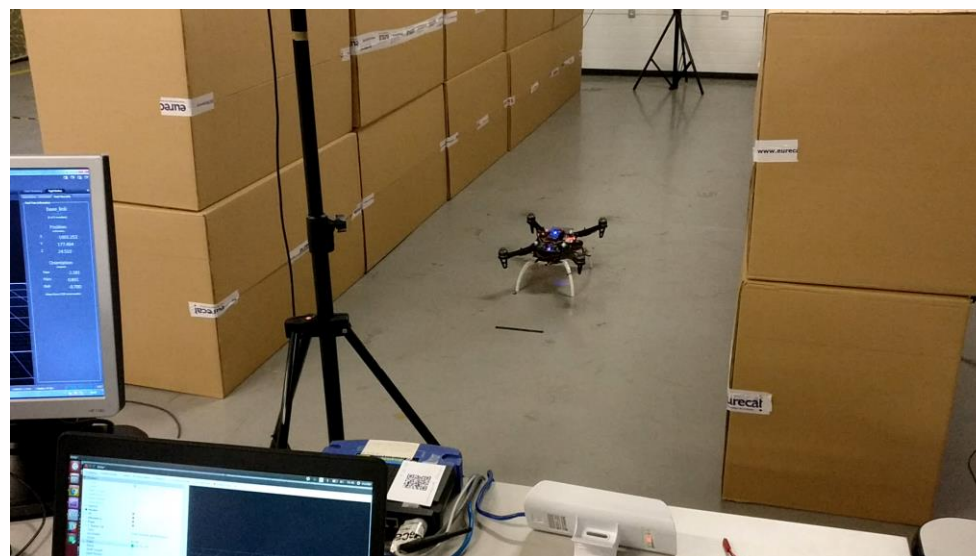
Specialized
Path Planners

Urban Robotics Challenge

Wall following

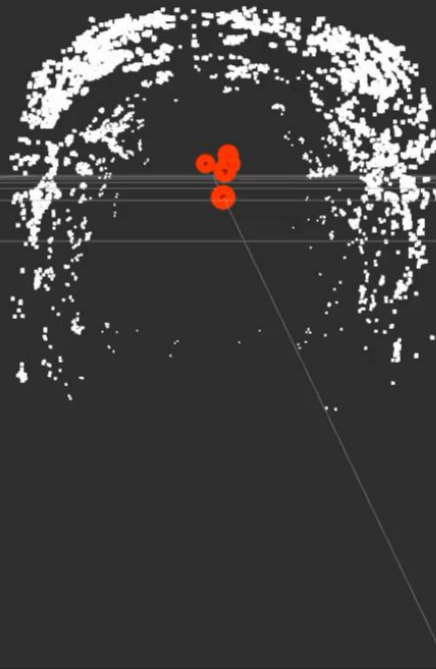


Tunnel following



Phase 2 Evaluating localization methods

Urban Robotics Challenge



Phase 2 Developing structural assessment

Urban Robotics Challenge



Next steps

Urban Robotics Challenge

Finalize localization, both local and global

Robustify specialized assistive planners

Develop structural assessment based on 3D reconstruction

Validate on the sewer



Thanks



Daniel Serrano
Head of Autonomous Systems
Eurecat Technology Center
Barcelona (Spain)
daniel.serrano@eurecat.org

